(T(5th Sm.)-Physics-H/DSE-A-1/CBCS)

# 2020

## **PHYSICS** — HONOURS

### Paper : DSE-A-1

#### (Advanced Mathematical Methods Theory)

#### Full Marks : 65

The figures in the margin indicate full marks. Candidates are required to give their answers in their own words as far as practicable.

Answer question nos. 1 & 2, and any four questions from the rest (Q.3 to Q.8).

1. Answer any five questions :

2×5

- (a) If  $P_1$  and  $P_2$  are two projection operators, then under what condition is  $P_1 + P_2$  also behaves like a projection operator?
- (b) Show that any two vectors  $|V_1\rangle$  and  $|V_2\rangle$  ( $\neq 0$ ) that are orthogonal to each other are linearly independent.
- (c) Use transformation property of cartesian tensors to establish that every contraction reduces the rank of a tensor by 2.
- (d) Show that  $\delta_i^1$  is an isotropic tensor.
- (e) If  $|q\rangle$  is any eigenstate of operator  $\hat{Q}$  such that  $\hat{Q}|q\rangle = q|q\rangle$  and suppose that  $\hat{C}$  is another operator with  $\hat{C}|q\rangle = |-q\rangle$ , show that  $\hat{C}\hat{Q} = -\hat{Q}\hat{C}$ .
- (f) The line element in metric form is given by  $ds^2 = g_{\mu\nu}dx^{\mu}dx^{\nu}$ . Use Quotient law to argue that  $g_{\mu\nu}$  is a covariant tensor of rank two.
- (g) Let  $e_1$ ,  $e_2$ ,  $e_3$  be the generators of a three dimensional Lie algebra with the commutation relation  $[e_1, e_2] = 0$ ,  $[e_2, e_3] = e_1 + e_2$ ;  $[e_3, e_1] = -e_1$ . Find  $[e_1, [e_2, e_3]] + [e_3, [e_1, e_2]]$ .
- 2. Answer any three questions :
  - (a) Given the set of vectors  $u_1 = (2, -1, 0)$ ,  $u_2 = (1, 0, -1)$ ,  $u_3 = (3, 7, -1)$ . Use Gram-Schmidt orthogonalization procedure, with the standard Euclidean inner product, to find an orthonormal set. 5

(b) Prove the vector identity 
$$(\vec{A} \times \vec{B}) \cdot (\vec{C} \times \vec{D}) = (\vec{A} \cdot \vec{C}) (\vec{B} \cdot \vec{D}) - (\vec{A} \cdot \vec{D}) (\vec{B} \cdot \vec{C})$$
  
using  $\epsilon_{ijk} \epsilon_{pqk} = \delta_{ip} \delta_{jq} - \delta_{iq} \delta_{jp}$ .

**Please Turn Over** 

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- (c) An antisymmetric tensor  $F_{\mu\nu}$  satisfies  $\partial_{\mu}F^{\mu\nu} = j^{\nu}$ .
  - (i) Show that  $\partial_{\nu} j^{\nu} = 0$ .
  - (ii) Find out the number of independent components of  $F_{\mu\nu}$  in 4 dimensions.

(2)

- (iii) Show that for any mixed tensor  $T_{\nu}^{\mu}$ ,  $T_{\mu}^{\mu}$  is a scalar. 2+1+2
- (d) (i) Show that all  $(n \times n)$  unitary matrices form a group under multiplication.
  - (ii) Show that all such matrices with determinant 1 forms a subgroup. 3+2
- (e) Show that all integers including zero form a group under addition. Write down the identity element. Do they form a group under subtraction? Justify. 2+1+2
- **3.** Show that the matrix  $A = \begin{pmatrix} 1 & -i \\ i & 1 \end{pmatrix}$ 
  - (a) is Hermitian.
  - (b) Find out its eigenvalues.
  - (c) Find out eigenvectors and show that they are orthogonal.
  - (d) Denoting the eigenvectors  $|1\rangle$  and  $|2\rangle$ , show that  $|1\rangle\langle 1|+|2\rangle\langle 2|=\mathbb{I}$ . 1+2+(3+1)+3

4. Starting with a vector space consisting of functions

 $f_0(x) = 1$ ,  $f_1(x) = x$ ,  $f_2(x) = x^2$ ,...,  $f_n(x) = x^n$  and defining the scalar product as

$$\langle f_m | f_n \rangle \equiv \int_{-1}^{1} f_m(x) f_n(x) dx$$

- (a) Show that these functions are not orthogonal to each other.
- (b) Starting from  $f_0(x)$  and  $f_1(x)$ , use Gram-Schmidt method to construct first three polynomials  $P_0(x)$ ,  $P_1(x)$  and  $P_2(x)$ .
- (c) Normalize these polynomials such that  $P_n(x=1) = 1$ .
- (d) Show that  $P_2(x)$  is an eigenfunction of the operator  $(1-x^2)\frac{d^2}{dx^2} 2x\frac{d}{dx}$ . Find the eigenvalue. 2+4+2+2
- 5. Consider two vectors (cartesian)  $\vec{A}$  and  $\vec{B}$  in 3D. For an anticlockwise rotation about the z-axis by an angle  $\theta$ .
  - (a) How do the components of the vectors change?

(3)

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2+2+5+1

(b) Show that for a norm-preserving rotation  $\sum_{i} A_i B_i$  is a scalar, using transformation properties.

(c) Define :

$$\begin{split} C_1 &\equiv A_2B_3 - A_3B_2\\ C_2 &\equiv A_3B_1 - A_1B_3\\ C_3 &\equiv A_1B_2 - A_2B_1 \end{split}$$

Show that under this rotation  $C_1$ ,  $C_2$ ,  $C_3$  transform like the components of a vector.

- (d) Identify  $\vec{C}$  in terms of  $\vec{A}$  and  $\vec{B}$ .
- 6. (a) Write down the Moment of Inertia tensor  $I_{ij}$  explaining each term.
  - (b) Show that  $I_{ij}$  is symmetric.
  - (c) Show that  $I_{ij}$  transforms as a 2nd rank tensor.
  - (d) Construct the inertia matrix for a system of three point masses of 1 unit, 2 units and 1 unit placed at (1, 1, -2), (-1, -1, 0) and (1, 1, 2) respectively.
- 7. (a) Construct the group multiplication table for the set of elements  $\{1, i, -1, -i\}$ . Find out the identity element. Find the inverse of the element *i* and -1.
  - (b) Consider  $\{1, -1\}$ . Show that they form a subgroup of the above group.
  - (c) Consider two matrices  $A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ ;  $B = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$ . Show that the map  $1 \to A$  and  $-1 \to B$  is a homomorphism. (3+1+2)+2+2
- 8. (a) Write down the generators for SU(2) group in fundamental representation.
  - (b) Find out the non-zero structure constants.
  - (c) Find out the adjoint representation of SU(2) group. 2+3+5